Regulation of Alternators

Phasor diagram of an alternator at lagging power factor is as follows.



Regulation is found by the following expression

% regn =
$$\frac{E_0 - V}{V} \times 100$$

where V is the terminal voltage and E_0 is the induced voltage. E_0 is estimated by one of the following methods.

EMF method

(Synchronous impedance method)

Tests:

Conduct tests to find OCC (upto 125% of rated voltage) SCC (for rated current)



- V = rated phase voltage
- *I_{sc}* = short circuit current corresponding to the field current producing the rated voltage

Synchronous impedance per phase,

$$Z_{s} = \frac{V}{I_{sc}}$$
$$X_{s} = \sqrt{Z_{s}^{2} - R_{a}^{2}}$$

For any load current *I* and phase angle Φ , find E₀ as the vector sum of *V*, *IR_a* and *IX_s*

For lagging power factor



$$E_0 = \sqrt{\left(V\cos\Phi + IR_a\right)^2 + \left(V\sin\Phi + IX_s\right)^2}$$

For unity power factor



For leading power factor



$$E_0 = \sqrt{\left(V\cos\Phi + IR_a\right)^2 + \left(V\sin\Phi - IX_s\right)^2}$$

MMF method

(Ampere turns method)

Tests:



Steps:

- 1. By suitable tests plot OCC and SCC
- 2. From the OCC find the field current I_{fl} to produce rated voltage, *V*.
- 3. From SCC find the magnitude of field current I_{f2} to produce the required armature current.
- 4. Draw I_{f2} at angle (90+ Φ) from I_{f1} , where Φ is the phase angle of current from voltage. If current is leading, take the angle of I_{f2} as (90- Φ).
- 5. Find the resultant field current, I_f and mark its magnitude on the field current axis.
- 6. From OCC. find the voltage corresponding to I_{f} , which will be E_0 .

ZPF method

(Potier method)

Tests: Conduct tests to find OCC (upto 125% of rated voltage) SCC (for rated current) ZPF (for rated current and rated voltage) Armature Resistance (if required)



Steps:

- 1. By suitable tests plot OCC and SCC
- 2. Draw tangent to OCC (air gap line)
- 3. Conduct ZPF test at full load for rated voltage and fix the point B.
- 4. Draw the line BH with length equal to field current required to produce full load current at short circuit.
- 5. Draw HD parallel to the air gap line so as to touch the OCC.
- 6. Draw DE parallel to voltage axis. Now, DE represents voltage drop IX_L and BE represents the field current required to overcome the effect of armature reaction.

Triangle BDE is called Potier triangle and X_L is the Potier reactance

7. Find E from V, IX_L and Φ . Consider R_a also if required. The expression to use is

$$E = \sqrt{\left(V\cos\Phi + IR_a\right)^2 + \left(V\sin\Phi + IX_L\right)^2}$$

- 8. Find field current corresponding to *E*.
- 9. Draw FG with magnitude equal to BE at angle $(90+\Psi)$ from field current axis, where Ψ is the phase angle of current from voltage vector *E* (internal phase angle).
- 10. The resultant field current is given by OG. Mark this length on field current axis.
- 11. From OCC find the corresponding E_0 .

ASA method

Tests:

Conduct tests to find OCC (upto 125% of rated voltage) SCC (for rated current) ZPF (for rated current and rated voltage) Armature Resistance (if required)

Steps:

- 1. Follow steps 1 to 7 as in ZPF method.
- 2. Find I_{f1} corresponding to terminal voltage V using air gap line (OF₁ in figure).
- 3. xDraw I_{f2} with length equal to field current required to circulate rated current during short circuit condition at an angle (90+ Φ) from I_{f1} . The resultant of I_{f1} and I_{f2} gives I_f (OF₂ in figure).
- 4. Extend OF_2 upto F so that F_2F accounts for the additional field current accounting for the effect of saturation. F_2F is found for voltage E as shown.
- 5. Project total field current OF to the field current axis and find corresponding voltage E_0 using OCC.

Slip Test

(for salient pole machines only)

Tests: Conduct tests to find X_d and X_q Armature Resistance (if required)

- 1. Energise the alternator with field unexcited and driven close to synchronous speed by a prime mover.
- 2. Measure the line voltage and line current of the alternator.
- 3. Find X_d and X_q by the following expressions

$$X_{d} = \frac{V_{\text{max}}}{\sqrt{3}I_{\text{min}}} \qquad X_{q} = \frac{V_{\text{min}}}{\sqrt{3}I_{\text{max}}}$$

4. Find I_d as follows

$$\Psi = \tan^{-1} \frac{\operatorname{Vsin} \Phi + \operatorname{IX}_{q}}{\operatorname{Vcos} \Phi + \operatorname{IR}_{a}} ; \quad I_{d} = I \sin \Psi$$

5. Then expression for E_0 is

$$E_0 = \left[(V \cos \Phi + IR_a)^2 + (V \sin \Phi + IX_q)^2 \right]^{\frac{1}{2}} + I_d (X_d - X_q)$$



